

Optimal transport for graph data

Barycenters and dictionary learning

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January 26 2022

Statistics & Computer Science Day for Data Science, Paris-Saclay

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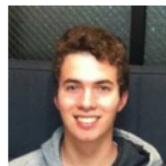
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Optimal Transport and divergences between graphs

Discrete Optimal Transport (OT)

Gromov-Wasserstein divergence and applications on graphs

Fused Gromov-Wasserstein and applications on attributed graphs

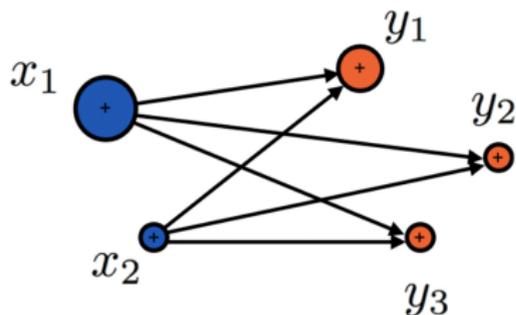
Online Graph Dictionary Learning

Linear modeling and unmixing of graphs

Learning a dictionary of graphs

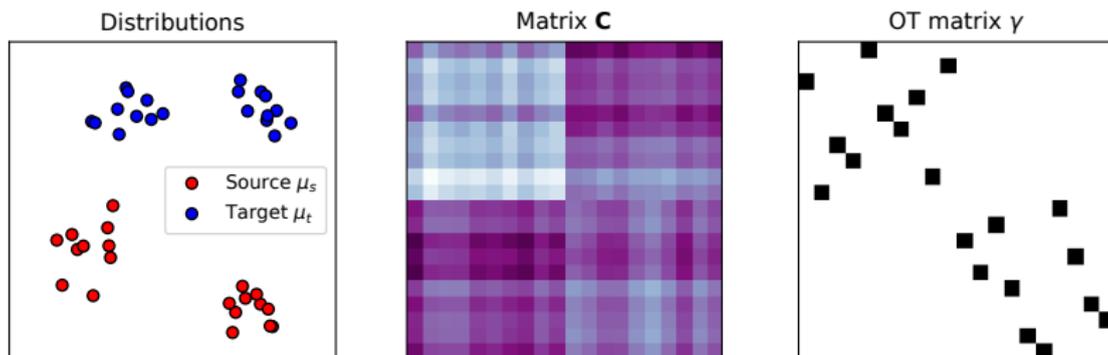
Numerical experiments

Optimal Transport and divergences between graphs



- Problem introduced by Gaspard Monge in his memoire [Monge, 1781].
- How to move mass while minimizing a cost (mass + cost)
- Monge formulation seeks for a mapping between two mass distribution.
- Reformulated by Leonid Kantorovich (1912–1986), Economy nobelist in 1975
- Focus on where the mass goes, allow splitting [Kantorovich, 1942].
- Applications originally for resource allocation problems

Optimal transport between discrete distributions



Kantorovitch formulation : OT Linear Program

When $\mu_s = \sum_{i=1}^{n_s} a_i \delta_{\mathbf{x}_i^s}$ and $\mu_t = \sum_{i=1}^{n_t} b_i \delta_{\mathbf{x}_i^t}$

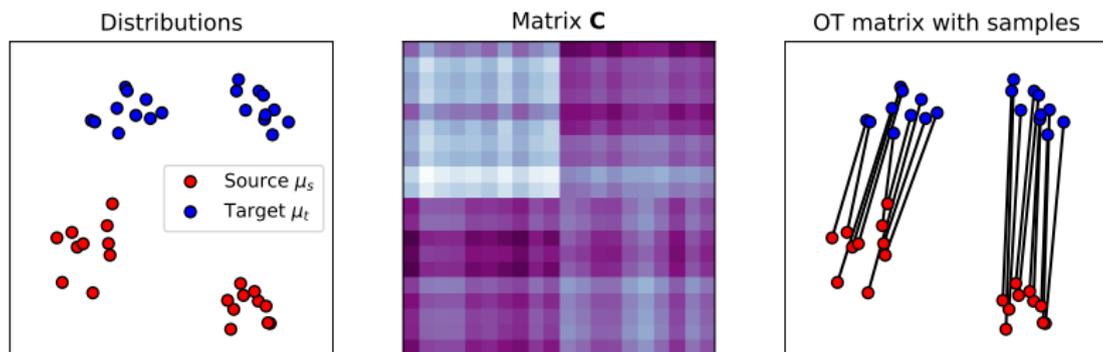
$$W_p^p(\mu_s, \mu_t) = \min_{\mathbf{T} \in \Pi(\mu_s, \mu_t)} \left\{ \langle \mathbf{T}, \mathbf{C} \rangle_F = \sum_{i,j} T_{i,j} c_{i,j} \right\}$$

where \mathbf{C} is a cost matrix with $c_{i,j} = c(\mathbf{x}_i^s, \mathbf{x}_j^t) = \|\mathbf{x}_i^s - \mathbf{x}_j^t\|^p$ and the constraints are

$$\Pi(\mu_s, \mu_t) = \left\{ \mathbf{T} \in (\mathbb{R}^+)^{n_s \times n_t} \mid \mathbf{T} \mathbf{1}_{n_t} = \mathbf{a}, \mathbf{T}^T \mathbf{1}_{n_s} = \mathbf{b} \right\}$$

- $W_p(\mu_s, \mu_t)$ is called the Wasserstein distance (EMD for $p = 1$).
- Entropic regularization solved efficiently with Sinkhorn [Cuturi, 2013].
- Classical OT needs distributions lying in the same space \rightarrow Gromov-Wasserstein.

Optimal transport between discrete distributions



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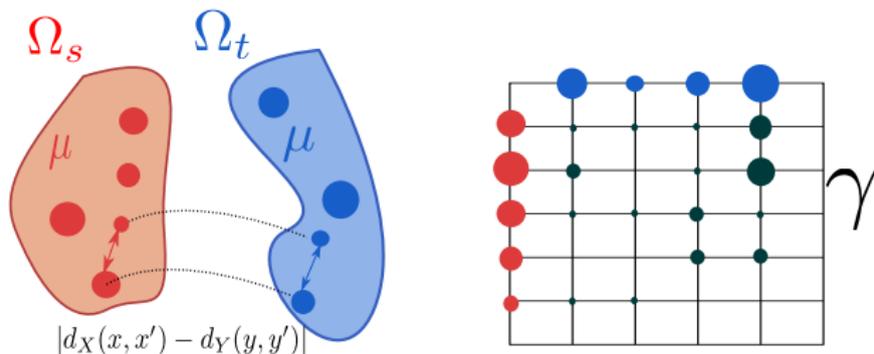
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Gromov-Wasserstein divergence



Inspired from Gabriel Peyré

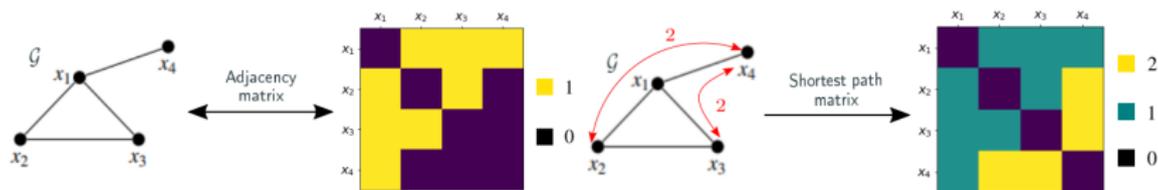
GW for discrete distributions [Memoli, 2011]

$$\mathcal{GW}_p(\mu_s, \mu_t) = \left(\min_{T \in \Pi(\mu_s, \mu_t)} \sum_{i,j,k,l} |D_{i,k} - D'_{j,l}|^p T_{i,j} T_{k,l} \right)^{\frac{1}{p}}$$

with $\mu_s = \sum_i a_i \delta_{\mathbf{x}_i^s}$ and $\mu_t = \sum_j b_j \delta_{\mathbf{x}_j^t}$ and $D_{i,k} = \|\mathbf{x}_i^s - \mathbf{x}_k^s\|$, $D'_{j,l} = \|\mathbf{x}_j^t - \mathbf{x}_l^t\|$

- Distance between metric measured spaces : across different spaces.
- Search for an OT plan that preserve the pairwise relationships between samples.
- Invariant to isometry in either spaces (e.g. rotations and translation).
- Entropy regularize GW proposed in [Peyré et al., 2016].

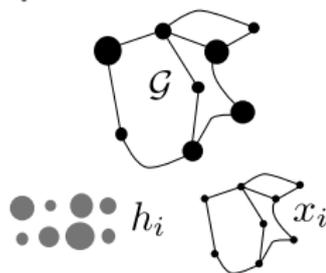
Gromov-Wasserstein between graphs



Modeling the graph structure with a pairwise matrix D

- An undirected graph $\mathcal{G} := (\mathbf{V}, \mathbf{E})$ is defined by $\mathbf{V} = \{\mathbf{x}_i\}_{i \in [\mathbf{N}]}$ set of the \mathbf{N} nodes and $\mathbf{E} = \{(\mathbf{x}_i, \mathbf{x}_j) | \mathbf{x}_i \leftrightarrow \mathbf{x}_j\}$ set of edges.
- Structure represented as a symmetric matrix D of relations between the nodes.
- Possible choices : **Adjacency matrix** (used in this study), Laplacian matrix, Shortest path or geodesic distance matrix.

Graph as a distribution (D, h)

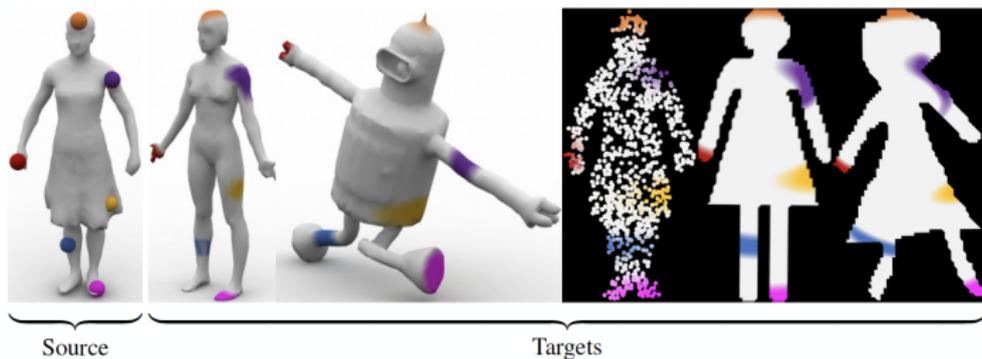


- Graph represented as a discrete distribution:

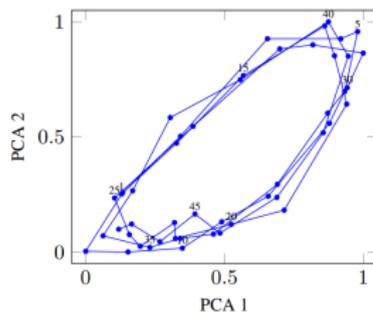
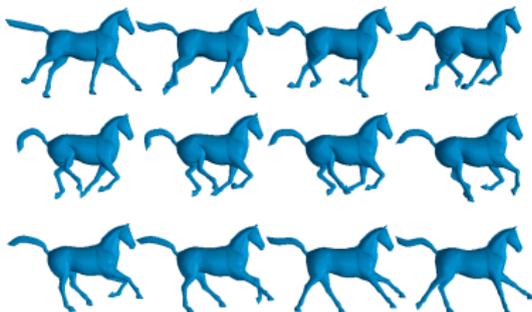
$$\mu_X = \sum_i h_i \delta_{x_i}$$

- The positions x_i are implicit and represented as the pairwise matrix D .
- h_i are the masses on the nodes of the graphs (uniform by default).

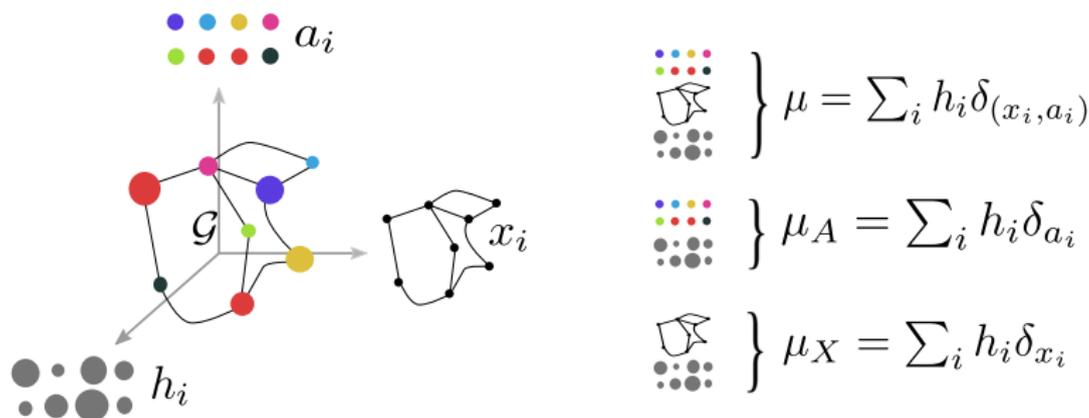
Shape matching between 3D and 2D surfaces



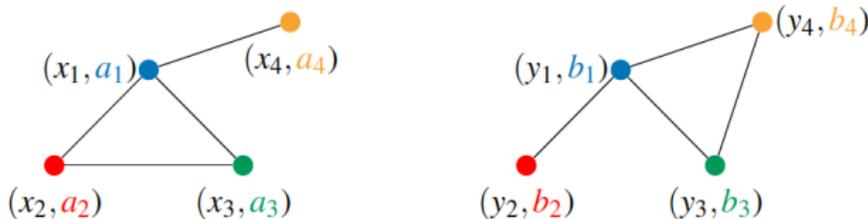
Multidimensional scaling (MDS) of shape collection



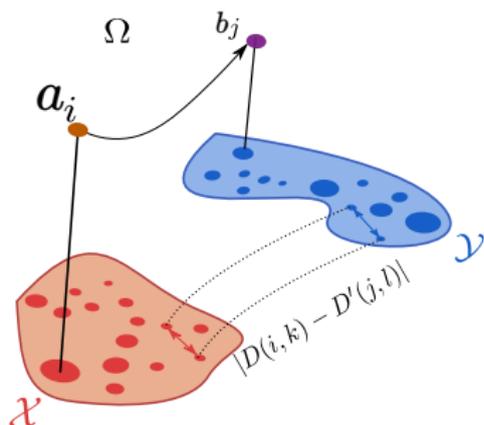
Attributed graphs as distributions



- Joint distribution μ in the feature/structure space.
 - Nodes are weighted by their mass h_i .
 - Structure encoded by x_i (no common metric between two different graphs).
 - Features values a_i can be compared through the common metric.
- Importance of the joint modeling:



Fused Gromov-Wasserstein distance



Fused Gromov Wasserstein distance [Vayer et al., 2020]

$$\mu_s = \sum_{i=1}^n h_i \delta_{x_i, a_i} \text{ and } \mu_t = \sum_{j=1}^m g_j \delta_{y_j, b_j}$$

$$\mathcal{FGW}_{p,q,\alpha}(D, D', \mu_s, \mu_t) = \left(\min_{T \in \Pi(\mu_s, \mu_t)} \sum_{i,j,k,l} ((1-\alpha)C_{i,j}^q + \alpha |D_{i,k} - D'_{j,l}|^q)^p T_{i,j} T_{k,l} \right)^{\frac{1}{p}}$$

with $D_{i,k} = \|x_i - x_k\|$ and $D'_{j,l} = \|y_j - y_l\|$ and $C_{i,j} = \|a_i - b_j\|$

- Parameters $q > 1, \forall p \geq 1$.
- $\alpha \in [0, 1]$ is a trade off parameter between structure and features.

$$\mathcal{FGW}_{p,q,\alpha}(D, D', \mu_s, \mu_t) = \left(\min_{T \in \Pi(\mu_s, \mu_t)} \sum_{i,j,k,l} ((1-\alpha)C_{i,j}^q + \alpha|D_{i,k} - D'_{j,l}|^q)^p T_{i,j} T_{k,l} \right)^{\frac{1}{p}}$$

Metric properties [Vayer et al., 2020]

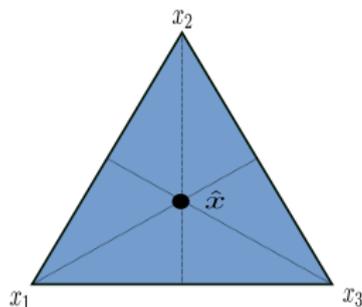
- \mathcal{FGW} defines a metric over structured data with **measure and features preserving isometries** as invariants.
- \mathcal{FGW} is a metric for $q = 1$ a semi metric for $q > 1$, $\forall p \geq 1$.
- The distance is nul *iff* :
 - There exists a Monge map $T \# \mu_s = \mu_t$.
 - Structures are equivalent through this Monge map (isometry).
 - Features are equal through this Monge map.

Bounds and convergence to finite samples [Vayer et al., 2020]

- $\mathcal{FGW}(\mu_s, \mu_t)$ is lower bounded by $(1 - \alpha)\mathcal{W}(\mu_A, \mu_B)^q$ and $\alpha\mathcal{GW}(\mu_X, \mu_Y)^q$
- Convergence of finite samples when $\mathcal{X} = \mathcal{Y}$ with $d = \text{Dim}(\mathcal{X}) + \text{Dim}(\Omega)$:

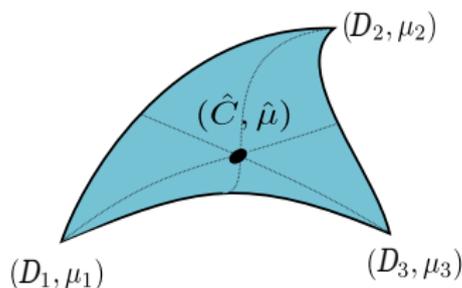
$$\mathbb{E}[\mathcal{FGW}(\mu, \mu_n)] = O\left(n^{-\frac{1}{d}}\right)$$

Euclidean barycenter



$$\min_x \sum_k \lambda_k \|x - x_k\|^2$$

FGW barycenter

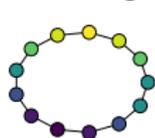


$$\min_{D \in \mathbb{R}^{n \times n}, \mu} \sum_i \lambda_i \mathcal{FGW}(D_i, D, \mu_i, \mu)$$

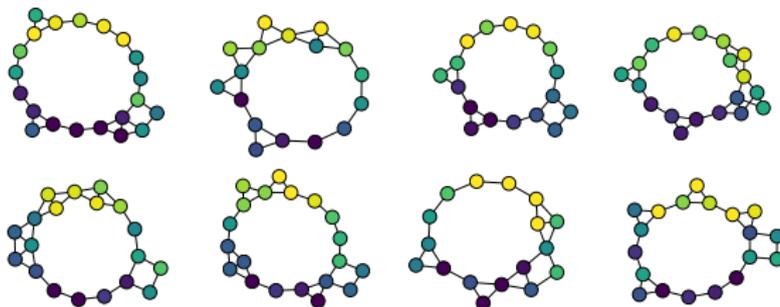
FGW barycenter $p = 1, q = 2$

- Estimate FGW barycenter using Frechet means (similar to [Peyré et al., 2016]).
- Barycenter optimization solved via block coordinate descent (on $\mathbf{T}, D, \{a_i\}_i$).
- Can chose to fix the structure (D) or the features $\{a_i\}_i$ in the barycenter.
- a_{ii} , and D updates are weighted averages using \mathbf{T} .

Noiseless graph



Noisy graphs samples



Barycenter of noisy graphs

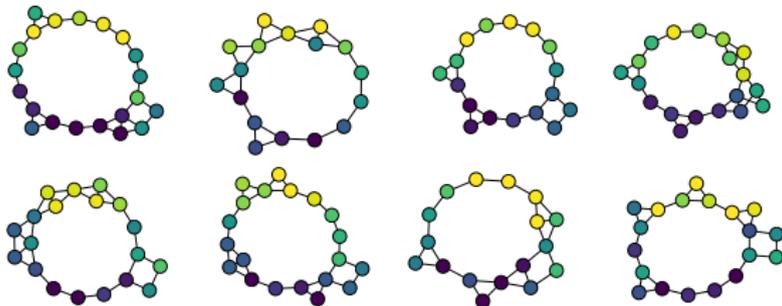
- We select a clean graph, change the number of nodes and add label noise and random connections.
- We compute the barycenter on $n = 15$ and $n = 7$ nodes.
- Barycenter graph is obtained through thresholding of the D matrix.

FGW barycenter on labeled graphs

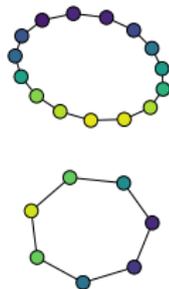
Noiseless graph



Noisy graphs samples



Barycenter



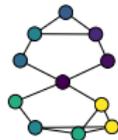
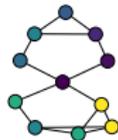
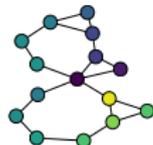
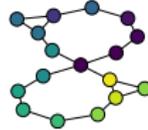
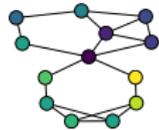
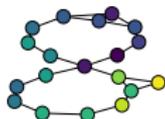
Barycenter of noisy graphs

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Noisy graphs samples

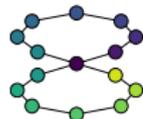


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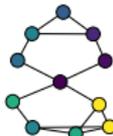
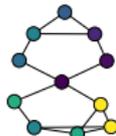
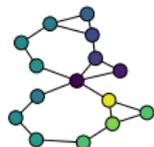
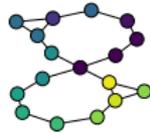
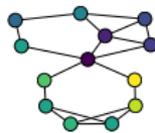
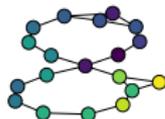
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FGW barycenter on labeled graphs

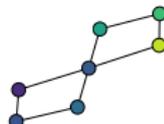
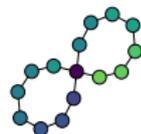
Noiseless graph



Noisy graphs samples



Barycenter

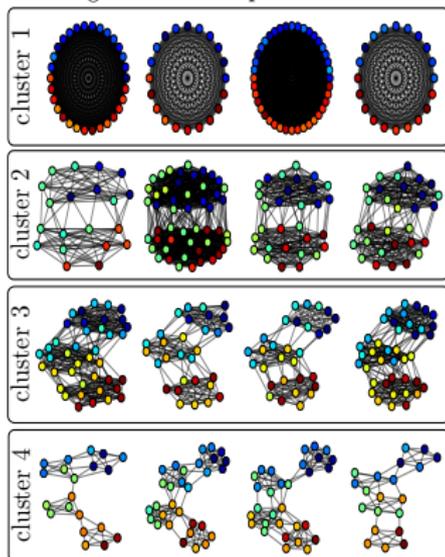


Barycenter of noisy graphs

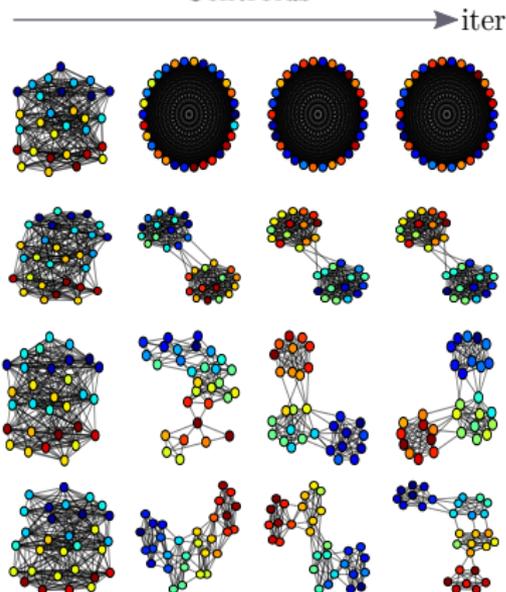
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FGW for graphs based clustering

Training dataset examples



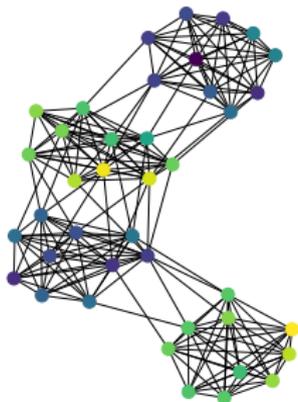
Centroids



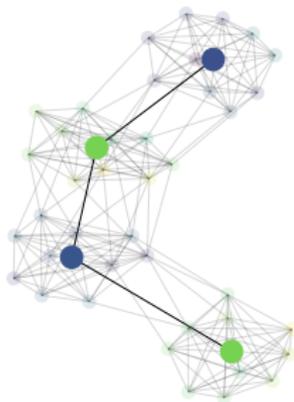
- Clustering of multiple real-valued graphs. Dataset composed of 40 graphs (10 graphs \times 4 types of communities)
- k -means clustering using the FGW barycenter

FGW barycenter for community clustering

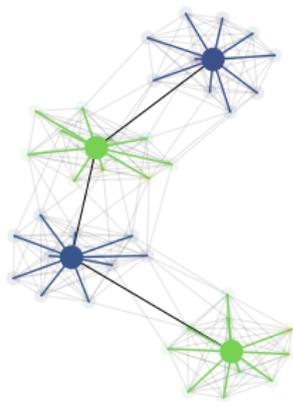
Graph with communities



Approximate Graph



Clustering with transport matrix

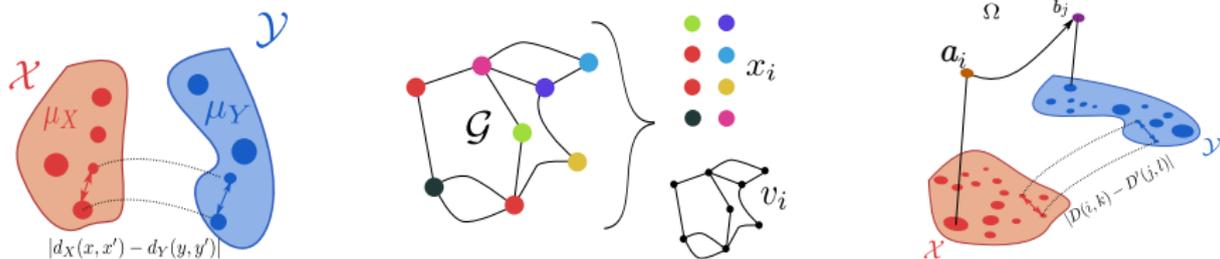


Graph approximation and community clustering

$$\min_{\mathbf{D}, \mu} \mathcal{FGW}(\mathbf{D}, \mathbf{D}_0, \mu, \mu_0)$$

- Approximate the graph (\mathbf{D}_0, μ_0) with a small number of nodes.
- Can be seen as a FGW (compressed) barycenter for one graph.
- OT matrix give the clustering affectation.
- Works for single and multiple modes in the clusters.

GW and FGW for graph modeling



Gromov-Wasserstein distance [Memoli, 2011]

- Divergence between distributions across metric spaces.
- Can be used to measure similarity between graphs seen as distribution their pairwise node relationship.

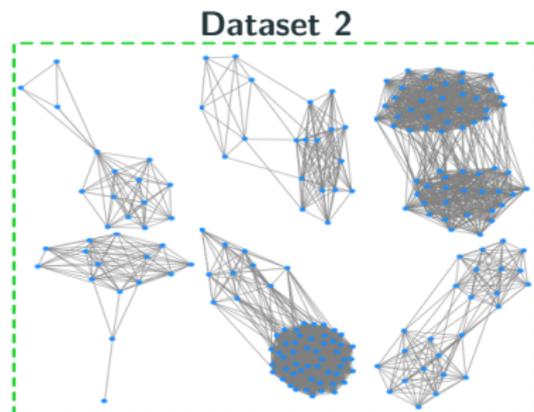
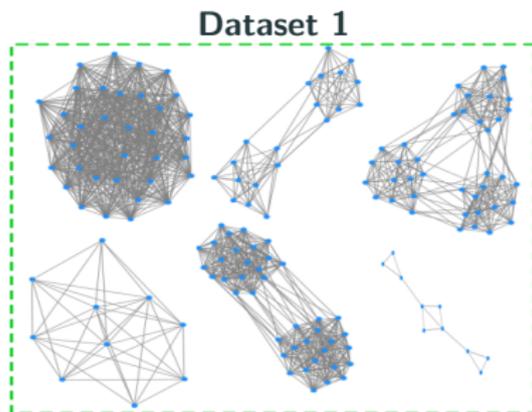
Fused Gromov-Wasserstein distance [Vayer et al., 2018]

- Model labeled structured data as joint structure/labels distributions.
- New versatile method for comparing structured data based on Optimal Transport
- New notion of barycenter of structured data such as graphs or time series

How to use GW/FGW to model data variability in a dataset of graphs?

Online Graph Dictionary Learning

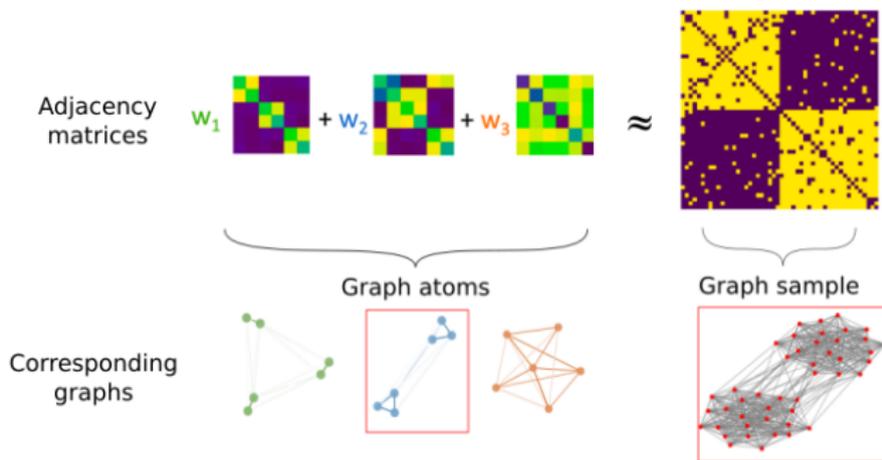
Datasets of graphs



SBM with balanced communities $\{1, 2, 3\}$.

Two communities of variable proportions.

- We have access to **large datasets of graphs** with variable number of nodes.
- How to model the variability of those graphs?
- A natural formulation is to use **factorization**.
- We propose to use a **linear** model for representing the graph associated to and estimation of the linear basis : **Dictionary learning**.

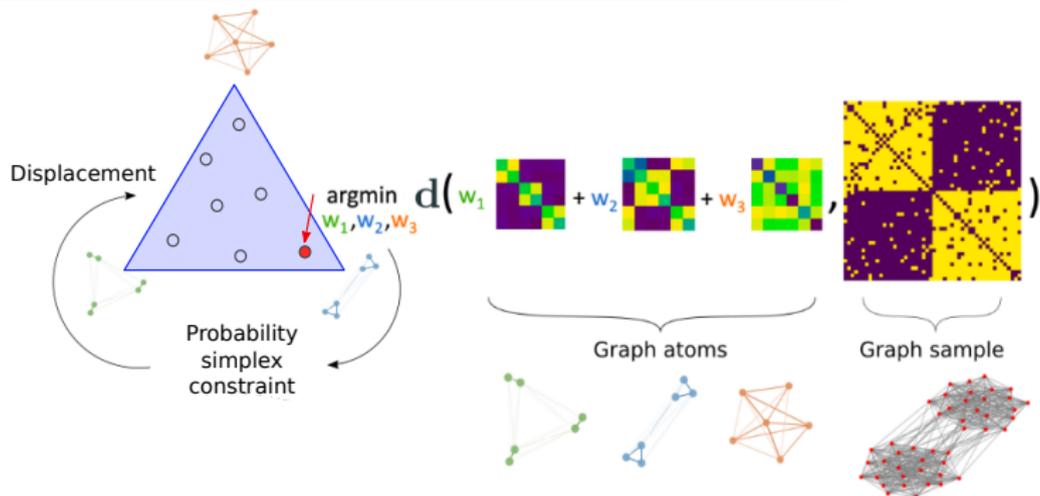


Linear modeling of graphs

$$D \approx \sum_{s \in [S]} w_s \overline{D}_s \quad (1)$$

- Approximate a given graph structure D as a non-negative weighted sum of template graphs \overline{D}_s .
- $\mathbf{w} \in \Sigma_S$ are the weights in the simplex.
- $\{\overline{D}_s\}_s$ is the dictionary of templates that all have the same order (nb. of nodes).

Gromov-Wasserstein Linear unmixing

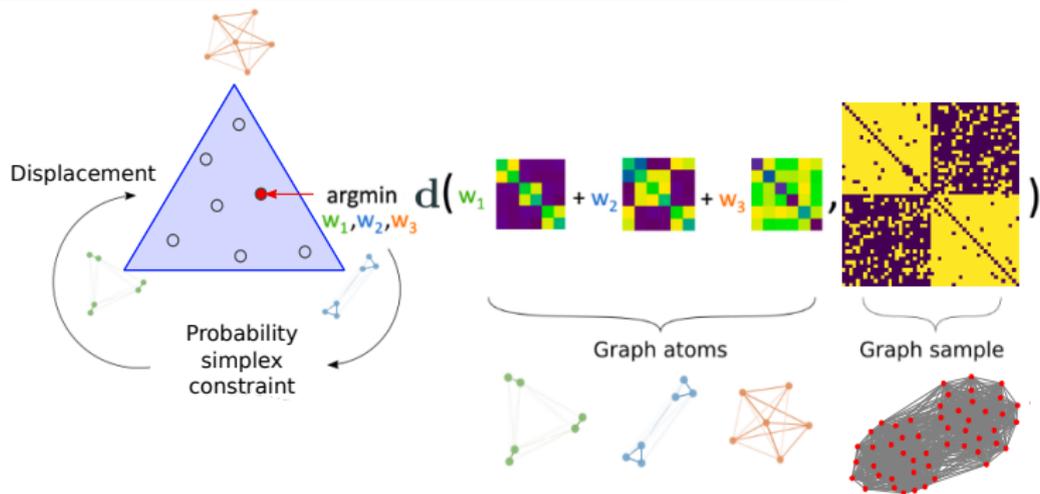


Sparse linear unmixing with Gromov-Wasserstein

$$\min_{\mathbf{w} \in \Sigma_S} \mathcal{GW}_2^2 \left(\sum_{s \in [S]} w_s \overline{D}_s, D \right) \quad (2)$$

- Estimate the linear representation on the simplex \mathbf{w} minimizing the GW distance *w.r.t.* the target graph D (non-negative unmixing).
- \mathbf{w} is a vector embedding of the graph D in the dictionary.
- GW between graphs

Gromov-Wasserstein Linear unmixing

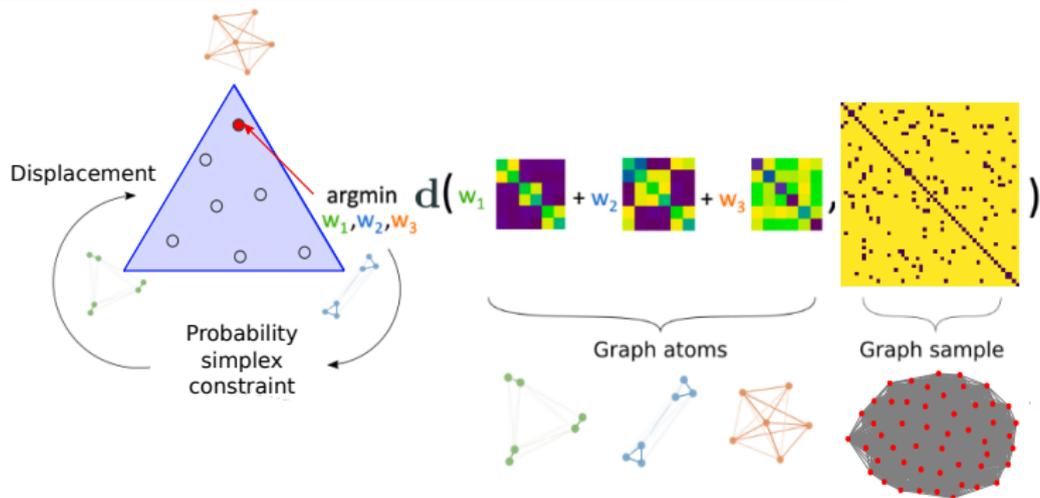


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Gromov-Wasserstein Linear unmixing



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GDL optimization problem

$$\min_{\{\mathbf{w}^{(k)}\}_{k \in [K]}, \{\overline{\mathbf{D}}_s\}_{s \in [S]}} \sum_{k=1}^K \mathcal{GW}_2^2 \left(\mathbf{D}^{(k)}, \sum_{s \in [S]} w_s^{(k)} \overline{\mathbf{D}}_s \right) - \lambda \|\mathbf{w}^{(k)}\|_2^2 \quad (3)$$

- On a dataset of K undirected graphs $\{\mathbf{D}^{(k)} \in S_{N^{(k)}}(\mathbb{R})\}_{k \in [K]}$.
- We want to estimate simultaneously the unmixing $\mathbf{w}^{(k)}$ of each graphs and the optimal dictionary $\{\overline{\mathbf{D}}_s\}_{s \in [S]}$.
- Very similar to classical DL (Non-negative Matrix Factorization) approach but with GW as a data fitting term.
- We propose to solve it an adaptation of the online algorithm [Mairal et al., 2009]

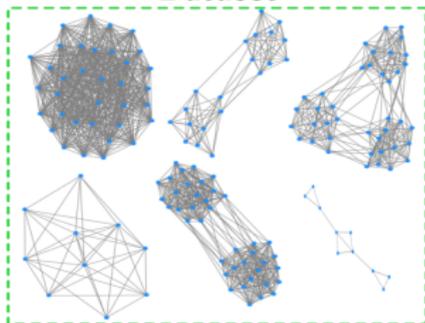
Stochastic/Online update [Vincent-Cuaz et al., 2021]

- 1: Sample a minibatch of graphs $\mathcal{B} := \{\mathbf{D}^{(k)}\}_{k \in \mathcal{B}}$.
- 2: Compute $\{(\mathbf{w}^{(k)}, \mathbf{T}^{(k)})\}_{k \in [B]}$ from solving B independent unmixings.
- 3: Compute the gradient $\tilde{\nabla}_{\overline{\mathbf{D}}_s}$ on the minibatch with fixed $\{(\mathbf{w}^{(k)}, \mathbf{T}^{(k)})\}_{k \in [B]}$.
- 4: Projected gradient step, $\forall s \in [S], \overline{\mathbf{D}}_s \leftarrow Proj_{S_N(\mathbb{R})}(\overline{\mathbf{D}}_s - \eta_C \tilde{\nabla}_{\overline{\mathbf{D}}_s})$

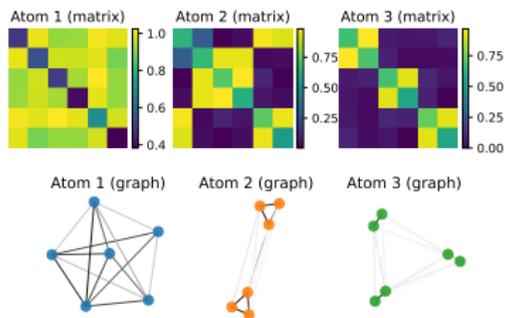
Experiments - Unsupervised representation learning

- Stochastic block model with $\{1, 2, 3\}$ blocks

Dataset

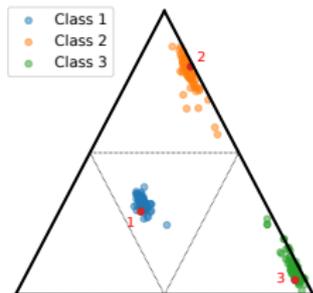


Learned atoms

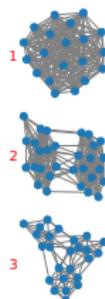


Embedding space

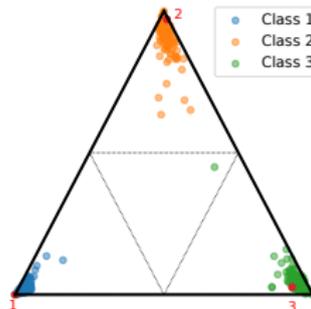
GDL unmixing $\mathbf{w}^{(k)}$ with $\lambda = 0$



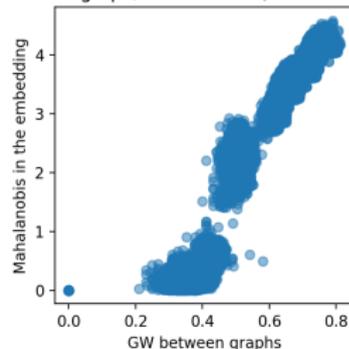
Examples



GDL unmixing $\mathbf{w}^{(k)}$ with $\lambda = 0.001$



GW graph/Mahalanobis (corr=0.96)

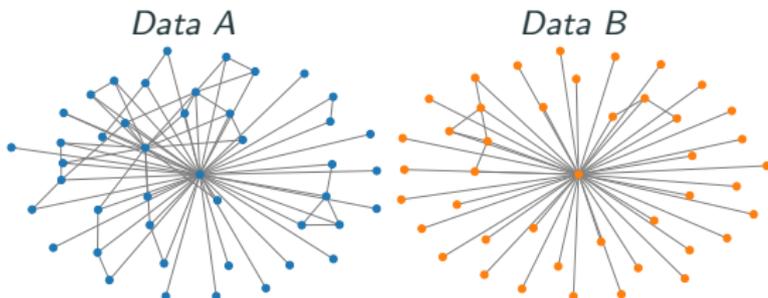


Experiments - Online Learning

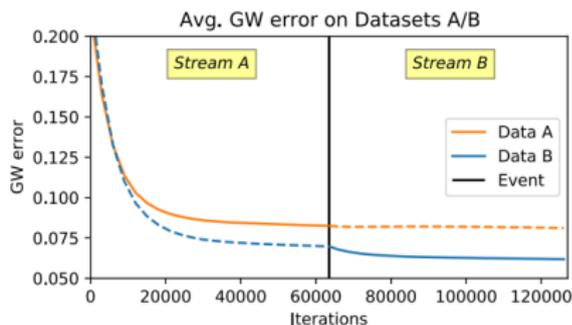
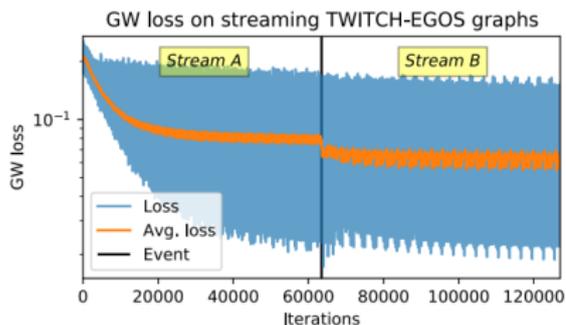
- **Streaming graphs:** Stochastic update for each new incoming graph

- Dataset: **TWITCH-EGOS**

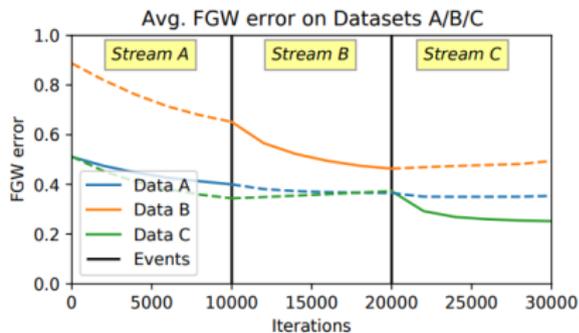
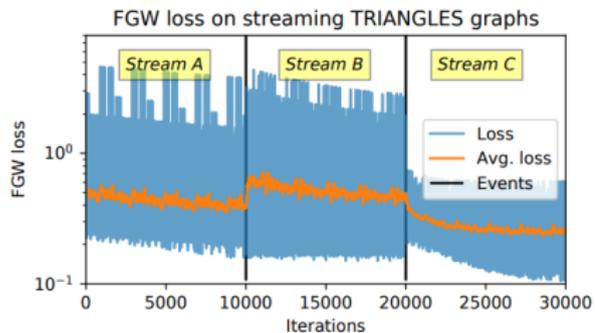
- 120.000+ graphs
- 2 classes
- shared hub structure



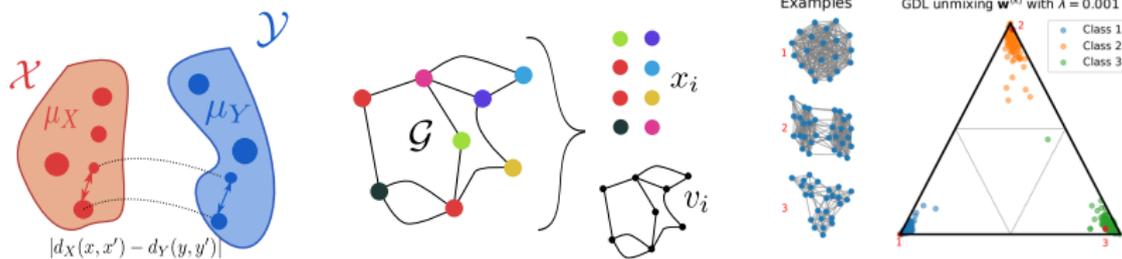
- **Simulated stream:** data A (class 1) \rightarrow data B (class 2)



- **Streaming graphs:** Stochastic update for each new incoming graph
- Dataset : **TRIANGLES**
 - 30.000+ labeled graphs
 - 10 classes
- **Simulated stream:** data A (4 classes) → data B (3 classes) → data C (3 classes)



Conclusion



Gromov-Wasserstein family for graph modeling

- Graphs modelled as distributions, \mathcal{GW} can measure their similarity.
- Extensions of GW for labeled graphs and Frechet means can be computed.
- Nonlinear and linear dictionaries of graphs using \mathcal{GW} provide a good modeling.
- Weights on the nodes are important but rarely available : relax the constraints [Séjourné et al., 2020] or even remove one of them [Vincent-Cuaz et al., 2022].

Open questions and new research

- Stability of the \mathcal{GW} plan to perturbations of \mathbf{D} (related to the GDL upper bound).
- Use \mathcal{GW} as a "kernel" for structured prediction (conditional \mathcal{GW} barycenters).

Python code available on GitHub:

<https://github.com/PythonOT/POT>

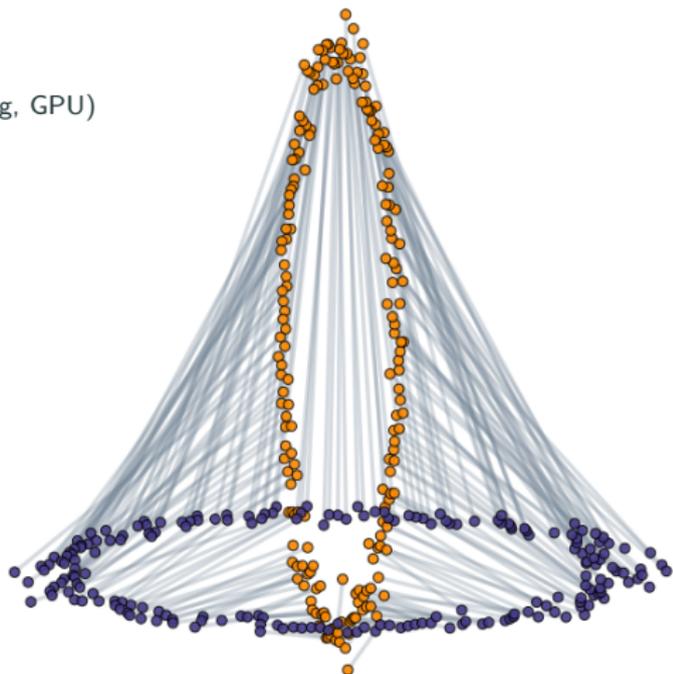
- OT LP solver, Sinkhorn (stabilized, ϵ -scaling, GPU)
- Domain adaptation with OT.
- Barycenters, Wasserstein unmixing.
- Wasserstein Discriminant Analysis.

Tutorial on OT for ML:

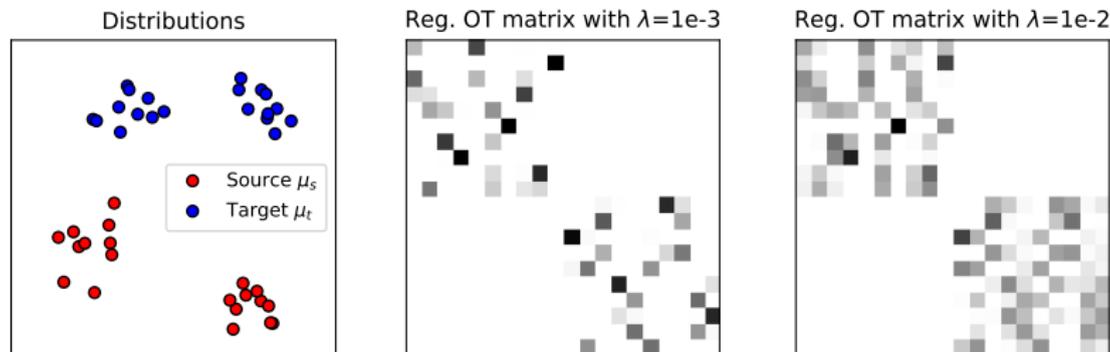
<http://tinyurl.com/otml-isbi>

Papers available on my website:

<https://remi.flamary.com/>



Entropic regularized optimal transport

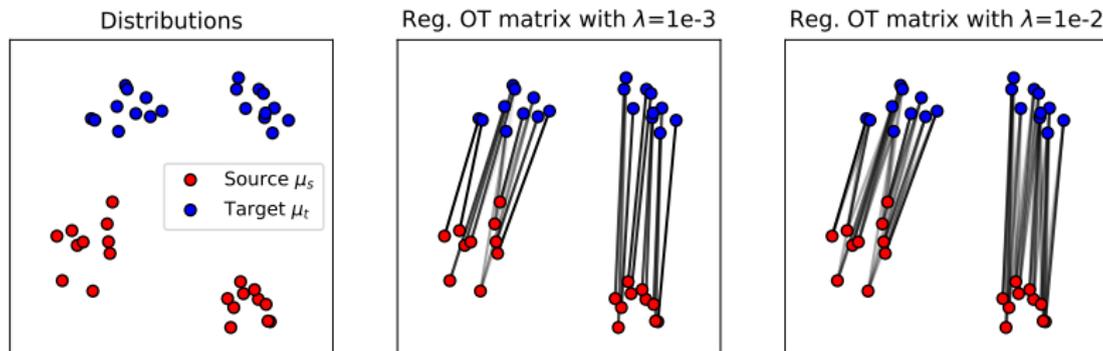


Entropic regularization [Cuturi, 2013]

$$W_\epsilon(\mu_s, \mu_t) = \min_{\mathbf{T} \in \Pi(\mu_s, \mu_t)} \langle \mathbf{T}, \mathbf{C} \rangle_F + \epsilon \sum_{i,j} T_{i,j} \log T_{i,j}$$

- Regularization with the negative entropy $-H(\mathbf{T})$.
- Looses sparsity, but strictly convex optimization problem [Benamou et al., 2015].
- Can be solved with the very efficient Sinkhorn-Knopp matrix scaling algorithm.
- Loss and OT matrix are differentiable and have better statistical properties [Genevay et al., 2018].

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GW Upper bound [Vincent-Cuaz et al., 2021]

Let two graphs of order N in the linear embedding $\left(\sum_s w_s^{(1)} \overline{\mathbf{D}}_s\right)$ and $\left(\sum_s w_s^{(2)} \overline{\mathbf{D}}_s\right)$, the \mathcal{GW} divergence can be upper bounded by

$$\mathcal{GW}_2 \left(\sum_{s \in [S]} w_s^{(1)} \overline{\mathbf{D}}_s, \sum_{s \in [S]} w_s^{(2)} \overline{\mathbf{D}}_s \right) \leq \|\mathbf{w}^{(1)} - \mathbf{w}^{(2)}\|_M \quad (4)$$

with M a PSD matrix of components $M_{p,q} = \langle \mathbf{D}_h \overline{\mathbf{D}}_p, \overline{\mathbf{D}}_q \mathbf{D}_h \rangle_F$, $\mathbf{D}_h = \text{diag}(\mathbf{h})$.

Discussion

- The upper bound is the value of GW for a transport $T = \text{diag}(\mathbf{h})$ assuming that the nodes are already aligned.
- The bound is exact when the weights $\mathbf{w}^{(1)}$ and $\mathbf{w}^{(2)}$ are close.
- Solving \mathcal{GW} with FW is $O(N^3 \log(N))$ at each iterations.
- Computing the Mahalanobis upper bound is $O(S^2)$: very fast alternative to GW for nearest neighbors retrieval.

Solving the Gromov Wasserstein optimization problem

Optimization problem

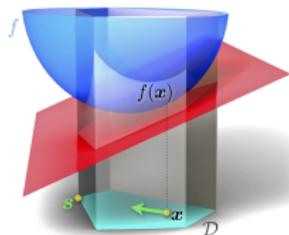
$$\mathcal{GW}_p^p(\mu_s, \mu_t) = \min_{\mathbf{T} \in \Pi(\mu_s, \mu_t)} \sum_{i,j,k,l} |D_{i,k} - D'_{j,l}|^p T_{i,j} T_{k,l}$$

with $\mu_s = \sum_i a_i \delta_{\mathbf{x}_i^s}$ and $\mu_t = \sum_j b_j \delta_{\mathbf{x}_j^t}$ and $D_{i,k} = \|\mathbf{x}_i^s - \mathbf{x}_k^s\|$, $D'_{j,l} = \|\mathbf{x}_j^t - \mathbf{x}_l^t\|$

- Quadratic Program (Wasserstein is a linear program).
- Nonconvex, NP-hard, related to Quadratic Assignment Problem (QAP).
- Large problem and non convexity forbid standard QP solvers.

Optimization algorithms

- Local solution with conditional gradient algorithm (Frank-Wolfe) [Frank and Wolfe, 1956].
- Each FW iteration requires solving an OT problems.
- Gromov in 1D has a close form (solved in discrete with a sort) [Vayer et al., 2019].
- With entropic regularization, one can use mirror descent [Peyré et al., 2016] or fast low rank approximations [Scetbon et al., 2021].



Optimization Problem

$$\mathcal{GW}_{p,\epsilon}^p(\mu_s, \mu_t) = \min_{\mathbf{T} \in \Pi(\mu_s, \mu_t)} \sum_{i,j,k,l} |D_{i,k} - D'_{j,l}|^p T_{i,j} T_{k,l} + \epsilon \sum_{i,j} T_{i,j} \log T_{i,j} \quad (5)$$

with $\mu_s = \sum_i a_i \delta_{\mathbf{x}_i^s}$ and $\mu_t = \sum_j b_j \delta_{\mathbf{x}_j^t}$ and $D_{i,k} = \|\mathbf{x}_i^s - \mathbf{x}_k^s\|$, $D'_{j,l} = \|\mathbf{x}_j^t - \mathbf{x}_l^t\|$

- Smoothing the original GW with a convex and smooth entropic term.

Solving the entropic GW [Peyré et al., 2016]

- Problem (5) can be solved using a KL mirror descent.
- This is equivalent to solving at each iteration t

$$\mathbf{T}^{(t+1)} = \min_{\mathbf{T} \in \mathcal{P}} \left\langle \mathbf{T}, \mathbf{G}^{(t)} \right\rangle_F + \epsilon \sum_{i,j} T_{i,j} \log T_{i,j}$$

Where $G_{i,j}^{(t)} = 2 \sum_{k,l} |D_{i,k} - D'_{j,l}|^p T_{k,l}^{(t)}$ is the gradient of the GW loss at previous point $\mathbf{T}^{(k)}$.

- Problem above solved using a Sinkhorn-Knopp algorithm of entropic OT.
- Very fast approximation exist for low rank distances [Scetbon et al., 2021].

Optimization problem

$$\min_{\mathbf{w} \in \Sigma_S} \mathcal{GW}_2^2 \left(\sum_{s \in [S]} w_s \overline{\mathbf{D}}_s, \mathbf{D} \right) - \lambda \|\mathbf{w}\|_2^2$$

- Non-convex Quadratic Program *w.r.t.* \mathbf{T} and \mathbf{w} .
- GW for fixed \mathbf{w} already have an existing Frank-Wolfe solver.
- We proposed a Block Coordinate Descent algorithm

BCD Algorithm for sparse GW unmixing [Tseng, 2001]

- 1: **repeat**
 - 2: Compute OT matrix \mathbf{T} of $\mathcal{GW}_2^2(\mathbf{D}, \sum_s w_s \overline{\mathbf{D}}_s)$, with FW [Vayer et al., 2018].
 - 3: Compute the optimal \mathbf{w} given \mathbf{T} with Frank-Wolfe algorithm.
 - 4: **until** convergence
- Since the problem is quadratic optimal steps can be obtained for both FW.
 - BCD convergence in practice in a few tens of iterations.

GDL on labeled graphs

- For datasets with labeled graphs, one can learn simultaneously a dictionary on the structure $\{\overline{\mathbf{D}}_s\}_{s \in [S]}$ and a dictionary on the labels/features $\{\overline{\mathbf{F}}_s\}_{s \in [S]}$.
- Data fitting is Fused Gromov-Wasserstein distance \mathcal{FGW} , same stochastic algorithm.

Dictionary on weights

$$\min_{\substack{\{(\mathbf{w}^{(k)}, \mathbf{v}^{(k)})\}_k \\ \{(\overline{\mathbf{D}}_s, \overline{\mathbf{h}}_s)\}_s}} \sum_{k=1}^K \mathcal{GW}_2^2 \left(\mathbf{D}^{(k)}, \sum_s w_s^{(k)} \overline{\mathbf{D}}_s, \mathbf{h}^{(k)}, \sum_s v_s^{(k)} \overline{\mathbf{h}}_s \right) - \lambda \|\mathbf{w}^{(k)}\|_2^2 - \mu \|\mathbf{v}^{(k)}\|_2^2$$

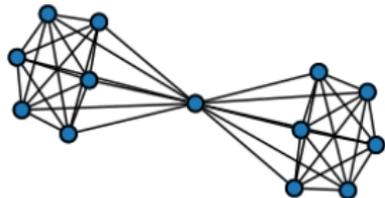
- We model the graphs as a linear model on the structure and the node weights

$$(\mathbf{D}^{(k)}, \mathbf{h}^{(k)}) \longrightarrow \left(\sum_s w_s^{(k)} \overline{\mathbf{D}}_s, \sum_s v_s^{(k)} \overline{\mathbf{h}}_s \right)$$

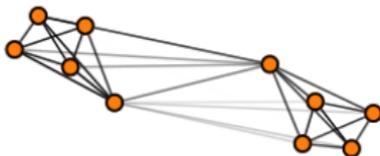
- This allows for sparse weights \mathbf{h} so embedded graphs with different order.
- We provide in [Vincent-Cuaz et al., 2021] subgradients of GW *w.r.t.* the mass \mathbf{h} .

Experiments - Unsupervised representation learning

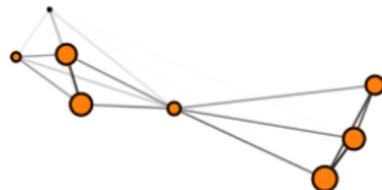
Graph from dataset



Model unif. \mathbf{h} (GW=0.09)



Model est. $\tilde{\mathbf{h}}$ (GW=0.08)



Comparison of fixed and learned weights dictionaries

- Graph taken from the IMBD dataset.
- Show original graph and representation after projection on the embedding.
- Uniform weight \mathbf{h} has a hard time representing a central node.
- Estimated weights $\tilde{\mathbf{h}}$ recover a central node.
- In addition some nodes are discarded with 0 weight (graphs can change order).

Table 1. Clustering: Rand Index computed for benchmarked approaches on real datasets.

models	no attribute		discrete attributes		real attributes			
	IMDB-B	IMDB-M	MUTAG	PTC-MR	BZR	COX2	ENZYMES	PROTEIN
GDL(ours)	51.64(0.59)	55.41(0.20)	70.89(0.11)	51.90(0.54)	66.42(1.96)	59.48(0.68)	66.97(0.93)	60.49(0.71)
GWF-r	51.24 (0.02)	55.54(0.03)	-	-	52.42(2.48)	56.84(0.41)	72.13(0.19)	59.96(0.09)
GWF-f	50.47(0.34)	54.01(0.37)	-	-	51.65(2.96)	52.86(0.53)	71.64(0.31)	58.89(0.39)
GW-k	50.32(0.02)	53.65(0.07)	57.56(1.50)	50.44(0.35)	56.72(0.50)	52.48(0.12)	66.33(1.42)	50.08(0.01)
SC	50.11(0.10)	54.40(9.45)	50.82(2.71)	50.45(0.31)	42.73(7.06)	41.32(6.07)	70.74(10.60)	49.92(1.23)

Clustering Experiments on real datasets

- Different data fitting losses:
 - Graphs without node attributes : Gromov-Wasserstein.
 - Graphs with node attributes (discrete and real): Fused Gromov-Wasserstein.
- We learn a dictionary on the dataset and perform K-means in the embedding using the Mahalanobis distance approximation.
- Compared to GW Factorization (GWF) [Xu, 2020] and spectral clustering.
- Similar performance for supervised classification (using GW in a kernel).

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